

Decidability of modal logics for dynamic contact relations

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Mereotopology

Mereotopology = Mereology + topological relations.

- mereology is an ontological discipline, theory of “Parts and Wholes”(see [9]);
- main relations in mereology: *part-of*, *overlap* and *underlap*;
- its mathematical equivalent are complete Boolean algebras without the zero element (Tarski, see [9]);
- the mathematical equivalent to mereotopology Contact algebras ([1], [2], [10]).

Contact algebras = Boolean algebras+contact-based relations.

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Contact algebras = Boolean algebras+contact-based relations.

Contact algebras - general definition

Definition (Contact algebra)

$(\underline{B}, C) = (B, 0, 1, \cdot, +, *, C)$ is called a *contact algebra* if \underline{B} is a Boolean algebra and C is a binary relation satisfying:

$$\begin{aligned} x C y &\implies x \neq 0 \& y \neq 0, & x C y &\implies y C x, \\ x C (y + z) &\iff x C y \text{ or } x C z, & x \cdot y \neq 0 &\implies x C y. \end{aligned}$$

Lemma

Let \mathbb{X} be a topological space. Then (\underline{B}, C) is a contact algebra, where \underline{B} is the Boolean algebra of the regular closed sets of \mathbb{X} and C is the topological contact in \mathbb{X} .

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Contact algebras - standard definition

Lemma

Let (X, R) be a frame, where R is a reflexive and symmetric relation. (\underline{B}, C) is a contact algebra, where \underline{B} is the Boolean algebra of the subsets of X and C is defined for $x, y \subseteq W$:

$$x C y \quad \text{iff} \quad \exists a \in x, \exists b \in y, a R b.$$

Definition (Mereotopological structure)

Let $(B, 0, 1, \cdot, +, *, C)$ be a contact algebra.

$\underline{W} = (W, \leq, O, U, C)$ a (static) mereotopological structure if $W \neq \emptyset$, $W \subseteq B$ and \leq , O and U are defined

$$x \leq y \text{ iff } x.y* = 0, \quad x O y \text{ iff } x.y \neq 0, \quad x U y \text{ iff } x + y \neq 1.$$

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Stable and unstable relations - standard definition

Definition (Standard dynamic mereotopological structure)

Let $I \neq \emptyset$ and for every $i \in I$, $\underline{W}_i = (W_i, \leq_i, O_i, U_i, C_i)$ be a static structure. Let $W \subseteq \prod_{i \in I} W_i$, $W \neq \emptyset$. Then for $x, y \in W$:

$x \leq y$	iff	$\forall i \in I, x_i \leq_i y_i$	<i>stable part-of,</i>
$x o y$	iff	$\forall i \in I, x_i O_i y_i$	<i>stable overlap,</i>
$x u y$	iff	$\forall i \in I, x_i U_i y_i$	<i>stable underlap,</i>
$x c y$	iff	$\forall i \in I, x_i C_i y_i$	<i>stable contact,</i>
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Intuition

The intuition behind the formal definition is

- I are the moments of time;
- \underline{W}_i are snapshots of the environment;
- $x \in W$ are histories of changing regions;
- *stable* means *always*;
- *unstable* means *sometimes*.

Integrated language of spacial and temporal primitives, which cannot be considered independantly (ideas of Whitehead [11] and de Laguna [4]).

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Stable and unstable relations - general definition

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$(W, \leq, o, u, c, \preceq, O, U, C)$ is a *dynamic structure* if it satisfies:

$$(M1) x \leq x$$

$$(M2) x \leq y \& y \leq z \Rightarrow x \leq z$$

$$(M3) x \leq y \& y \leq x \Rightarrow x = y$$

$$(M4) x O y \Rightarrow y O x$$

$$(M5) x O y \Rightarrow x O x$$

$$(M6) x O y \& y \leq z \Rightarrow x O z$$

$$(M7) x O x \text{ or } x \leq y$$

$$(M8) x U y \Rightarrow y U x$$

$$(M9) x U y \Rightarrow x U x$$

$$(M10) x \leq y \& y U z \Rightarrow x U z$$

$$(C1) x C y \Rightarrow y C x$$

$$(C2) x O y \Rightarrow x C y$$

$$(C3) x C y \Rightarrow x O x$$

$$(C10) z c t \& x \bar{u} y \& z \bar{O} y \& t \bar{O} x \Rightarrow x C y$$

$$(M11) y U y \text{ or } x \leq y$$

$$(M12) x \leq y \text{ or } x O z \text{ or } y U z$$

$$(M13) x O x \text{ or } x U x$$

$$(M14) x \preceq x$$

$$(M15) x \leq y \& y \preceq z \Rightarrow x \preceq z$$

$$(M16) x \preceq y \& y \leq z \Rightarrow x \preceq z$$

$$(M17) x o y \Rightarrow y o x$$

$$(M18) x o y \Rightarrow x o x$$

$$(M19) x o y \& y \leq z \Rightarrow x o z$$

$$(M20) x o y \& y \preceq z \Rightarrow x O z$$

$$(C4) x C y \& y \leq z \Rightarrow x C z$$

$$(C5) x c y \Rightarrow y c x$$

$$(C6) x o y \Rightarrow x c y$$

$$(M21) x o x \text{ or } x \preceq y$$

$$(M22) x o z \text{ or } y U z \text{ or } x \preceq y$$

$$(M23) x u y \Rightarrow y u x$$

$$(M24) x u y \Rightarrow x u x$$

$$(M25) x \leq y \& y u z \Rightarrow x u z$$

$$(M26) x \preceq y \& y u z \Rightarrow x U z$$

$$(M27) x O z \text{ or } y u z \text{ or } x \preceq y$$

$$(M28) y u y \text{ or } x \preceq y$$

$$(M29) x o x \text{ or } x U x$$

$$(M30) x O x \text{ or } x u x$$

$$(C7) x c y \Rightarrow x o x$$

$$(C8) x c y \& y \leq z \Rightarrow x c z$$

$$(C9) x c y \& y \preceq z \Rightarrow x C z$$

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The first-order logic

Two classes: the standard structures - Σ_{std} , and the general structures - Σ_{gen} . Results ([5], [6], [7]):

- $FOL(\Sigma_{\text{std}}) = FOL(\Sigma_{\text{gen}})$;
- $FOL(\Sigma_{\text{std}})$ is complete w.r.t. (M1)-(M30), (C1)-(C10);
- $FOL(\Sigma_{\text{std}})$ (or $FOL(\Sigma_{\text{gen}})$ respectively) is hereditary undecidable (see [3]);
- the quantifier-free fragment of this logic is complete;
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The logic, axioms, definability

The polymodal logic of Σ_{std} and the universal relation A.

(M1)-(M30), (C1)-(C10) are definable, but (M3). Replace it with:

(M3') $x \bar{O} x$ and $y \leq x \Rightarrow x = y$

(M3'') $x \bar{U} x$ and $x \leq y \Rightarrow x = y$

(M3''') $z \bar{O} x$ and $z \bar{U} y$ and $y \leq x \Rightarrow x = y$

Definition

$(W, \leq, o, u, c, \preceq, O, U, C)$ is a *non-standard structure* if it satisfies (M1), (M2), (M3'), (M3''), (M3'''), (M4)-(M30), (C1)-(C10).

These structures form Σ_{nonstd} .

Lemma (P-morphism lemma)

For every non-standard structure \underline{W} there is a general structure \underline{W}' and a p -morphism from \underline{W} onto \underline{W}' .

Proved via a generalization of Segerberg's Bulldozer method.

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Completeness

Theorem (Completeness theorem)

The following propositions are equivalent for every formula α :

- (1) α is theorem of the logic;*
- (2) α is true in every non-standard structure from Σ_{nonstd} ;*
- (3) α is true in every general structure from Σ_{gen} ;*
- (4) α is true in every standard structure from Σ_{std} .*

See [5], [7], [8] for detailed proofs. Here is a sketch:

- (1) \longrightarrow (2): soundness;
- (1) \longleftarrow (2): generated canonical models;
- (2) \longrightarrow (3): every general structure is non-standard;
- (2) \longleftarrow (3): P-morphism lemma;
- (3) \longrightarrow (4): every standard structure is general;
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See [5], [7], [8] for detailed proofs. Here is a sketch:

- (1) \longrightarrow (2): soundness;
- (1) \longleftarrow (2): generated canonical models;
- (2) \longrightarrow (3): every general structure is non-standard;
- (2) \longleftarrow (3): P-morphism lemma;
- (3) \longrightarrow (4): every standard structure is general;
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Theorem (Completeness theorem)

The following propositions are equivalent for every formula α :

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The first reduct

The logic with the unstable contact C , without the stable contact c . Models of the form $\underline{W} = (W, \leq, o, u, \preceq, O, U, C)$.

Filtration: start from reduct model (\underline{W}, ν) and set of formulae Γ .

1. Γ is closed under sub-formulae;
2. $\langle R \rangle T \in \Gamma$ for each of the modalities o, u, O and U where T is an arbitrary fixed MLDM tautology;
3. if $[R]\alpha \in \Gamma$ for some modality R then $[R]\alpha \in \Gamma$ for all modalities of the logic.

We build the filtered finite model (\underline{W}', ν') in the standard way.

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We build the filtered finite model (\underline{W}', ν') in the standard way.

The filtration - relations \leq and \preceq

Relation \leq' : $[x] \leq' [y]$ holds iff the following conditions are met

$$v(x, \langle O \rangle T) = 1 \text{ implies } v(y, \langle O \rangle T) = 1,$$

$$v(x, \langle o \rangle T) = 1 \text{ implies } v(y, \langle o \rangle T) = 1,$$

$$v(x, [\leq]\alpha) = 1 \text{ implies } v(y, [\leq]\alpha) = 1,$$

$$v(y, [O]\alpha) = 1 \text{ implies } v(x, [O]\alpha) = 1,$$

$$v(x, [\preceq]\alpha) = 1 \text{ implies } v(y, [\preceq]\alpha) = 1,$$

$$v(y, [o]\alpha) = 1 \text{ implies } v(x, [o]\alpha) = 1,$$

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$$v(y, \langle u \rangle T) = 1 \text{ implies } v(x, \langle u \rangle T) = 1,$$

$$v(y, [\geq]\alpha) = 1 \text{ implies } v(x, [\geq]\alpha) = 1,$$

$$v(x, [U]\alpha) = 1 \text{ implies } v(y, [U]\alpha) = 1,$$

$$v(y, [\succeq]\alpha) = 1 \text{ implies } v(x, [\succeq]\alpha) = 1,$$

$$v(x, [u]\alpha) = 1 \text{ implies } v(y, [u]\alpha) = 1,$$

$$v(y, [c]\alpha) = 1 \text{ implies } v(x, [c]\alpha) = 1.$$

Relation \preceq' : $[x] \preceq' [y]$ iff

$$v(x, \langle o \rangle T) = 1 \text{ implies } v(y, \langle O \rangle T) = 1,$$

$$v(x, [\preceq]\alpha) = 1 \text{ implies } v(y, [\leq]\alpha) = 1,$$

$$v(y, [O]\alpha) = 1 \text{ implies } v(x, [o]\alpha) = 1,$$

$$v(y, [C]\alpha) = 1 \text{ implies } v(x, [c]\alpha) = 1.$$

$$v(y, \langle u \rangle T) = 1 \text{ implies } v(x, \langle U \rangle T) = 1,$$

$$v(y, [\succeq]\alpha) = 1 \text{ implies } v(x, [\geq]\alpha) = 1,$$

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$$v(y, [O] \alpha) = 1 \text{ implies } v(x, [O] \alpha) = 1,$$

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$$v(y, [C] \alpha) = 1 \text{ implies } v(x, [C] \alpha) = 1,$$

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The filtration - relations o , O , u , U and C

Relation o' : $[x] o' [y]$ iff

$$v(x, \langle o \rangle \top) = 1$$

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The second reduct

The logic with both contacts, without the unstable part-of \preceq .
Models of the form $\underline{W} = (W, \leq, o, u, c, O, U, C)$.

Filtration: start from reduct model (\underline{W}, ν) and Γ .

1. Γ is closed under sub-formulae;
2. if $\alpha \in \Gamma$ and α does not start with $[\leq]$ (i.e. α is not in the form of $[\leq]\beta$) then $[\leq]\alpha \in \Gamma$ and $[\leq]\neg\alpha \in \Gamma$.

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The filtered finite model (\underline{W}', ν') is build standardly.

The filtration

Relation \leq' is defined standardly for S4 modality:

for all $[\leq]_\alpha \in \Gamma$, $v(x, [\leq]_\alpha) = 1$ implies $v(y, [\leq]_\alpha) = 1$.

$[x] O' [y] \leftrightarrow \exists z, t \in W, [z] \leq' [x], [t] \leq' [y]$ and $z O t$.

$[x] U' [y] \leftrightarrow \exists z, t \in W, [x] \leq' [z], [y] \leq' [t]$ and $z U t$.

$[x] o' [y] \leftrightarrow \exists z, t \in W, [z] \leq' [x], [t] \leq' [y]$ and $z o t$.

$[x] u' [y] \leftrightarrow \exists z, t \in W, [x] \leq' [z], [y] \leq' [t]$ and $z u t$.

$[x] c' [y] \leftrightarrow \exists z, t \in W, [z] \leq' [x], [t] \leq' [y]$ and $z c t$.

$[x] C' [y] \leftrightarrow \exists z, t \in W, [z] \leq' [x], [t] \leq' [y]$ and $z C t$.

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Open problems

Open problems and further development of the dynamic mereotopological relations and logics for them:

- the decidability of the full modal logic;
- the complexity of the modal logic (if it is decidable);
- the complexity of the decidable reducts;
- addition of more mereotopological relations;
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Thank you!!

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